# Divide and Conquer methods (and Branch and Bound) in a nutshell 

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## Introduction

Divide and conquer works by:

1. Breaking it into subproblems, that are themselves smaller instances of the same type of problem
2. Recursively solving these subproblems
3. Appropriately combining their answers
(from Dasgupta, Papadimitriou and Vazirani)

## Analyzing Divide and Conquer Methods

- Analyzing Divide and Conquer methods relies on analyzing recurrence relations, e.g.

$$
\begin{equation*}
T(n)=3 T(n / 2)+O(n) \tag{1}
\end{equation*}
$$

- The resulting complexity can be described using the following theorem:

Theorem
If $T(n)=a T(\lceil n / b\rceil)+O\left(n^{d}\right)$ for some constants $a>0, b>1$, and $d \geq 0$, then

$$
T(n)= \begin{cases}O\left(n^{d}\right) & \text { if } d>\log _{b} a  \tag{2}\\ O\left(n^{d} \log n\right) & \text { if } d=\log _{b} a \\ O\left(n^{\log _{b} a}\right) & \text { if } d<\log _{b} a\end{cases}
$$

## Merge Sort

- Merge sort works by

1. Diving the list in two
2. Calling merge sort on each half
3. Merging the sorted lists

- This has the recursion relation:

$$
\begin{equation*}
T(n)=2 T(\lceil n / 2\rceil)+O(n) \tag{3}
\end{equation*}
$$

because there are two calls to merge-sort , $2 T(\lceil n / 2\rceil)$, and the merge process takes $O(n)$

- From the Theorem, this gives a complexity of $O(n \log (n)$ which is very good.


## Matrix Multiplication

- Matrix multiplication was generally believed to be $O\left(n^{3}\right)$ ! For $Z=X Y$

$$
\begin{equation*}
z_{i k}=\sum_{j} x_{i j} Y_{j k} \tag{4}
\end{equation*}
$$

- Strassen discovered a more efficient divide and conquer approach. Instead of:

$$
X Y=\left[\begin{array}{ll}
A & B  \tag{5}\\
C & D
\end{array}\right]\left[\begin{array}{ll}
E & F \\
G & H
\end{array}\right]=\left[\begin{array}{ll}
A E+B G & A F+B H \\
C E+D G & C F+D H
\end{array}\right]
$$

- Which has recurrence relation $T(n)=8 T(n / 2)+O(n)^{2}$ and complexity $O\left(n^{3}\right)$


## Matrix Multiplication, cont'd

- The multiplication was expressed as:

$$
X Y=\left[\begin{array}{cc}
P_{5}+P_{4}-P_{2}+P_{6} & P_{1}+P_{2}  \tag{6}\\
P_{3}+P_{4} & P_{1}+P_{5}-P_{3}-P_{7}
\end{array}\right]
$$

where:

$$
\begin{array}{lll}
P_{1}=A(F-H) & P_{2}=(A+B) H & P_{3}=(C+D) E \\
P_{4}=D(G-E) & P_{5}=(A+D)(E+H) & P_{6}=(B-D)(G+H) \\
& & P_{7}=(A-C)(E+F) \tag{7}
\end{array}
$$

- The complexity is $T(n)=7 T(n / 2)+O\left(n^{2}\right)$, which is

$$
\begin{equation*}
O\left(n^{\log _{2} 7}\right) \approx O\left(n^{2.81}\right) \tag{8}
\end{equation*}
$$

## Other examples

- Fast fourier transform
- Nearest Neighbor search


## Branch and Bound

- Method to solve integer programming problems
- Simple example:

$$
\begin{array}{ll}
\text { minimize } & f(x, y) \\
\text { subject to } & g(x, y)=0  \tag{9}\\
& x \in\{0,1\} \\
& y \in\{0,1\}
\end{array}
$$

- Note that the optimal solution to

$$
\begin{array}{ll}
\operatorname{minimize} & f(x, y) \\
\text { subject to } & g(x, y)=0 \\
& x \in[0,1]  \tag{10}\\
& y \in\{0,1\}
\end{array}
$$

is a lower bound on the original ( $x$ has more choices).

## Branch and Bound, cont'd



- The lower bounds can be compared with a given feasible solution.
- This can reduce the number of solutions that need to be checked.

