# Estimation 

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## Introduction

What is estimation?
"Estimation is the process of extracting information from data data which can be used to infer the desired information and may contain errors."

- Arthur Gelb, Applied Optimal Estimation

Idea: extract information from noisy data

## Linear least squares and least norm estimates

- Assume no information on the probability distribution of the error
- Work with linear equations:

$$
\begin{equation*}
A x=b \tag{1}
\end{equation*}
$$

where $A$ and $b$ are known, and $x$ is a vector of unknowns

- Examples
- Linear least-squares fit of a data - fit a line to data
- Minimum norm fit - find the parameters that fit the data with minimum norm


## Linear least squares

Suppose we have an overdetermined set of equations:

$$
\begin{equation*}
A x=b \tag{2}
\end{equation*}
$$

where $|b|>|x|$ (there are more data points $b$ than parameters $x$ ). The estimate $\hat{x}$ that minimizes $\|A x-b\|_{2}$ is given by:

$$
\begin{equation*}
\hat{x}=\left(A^{T} A\right)^{-1} A^{T} b \tag{3}
\end{equation*}
$$

Proof.

$$
\begin{equation*}
\|A x-b\|_{2}=x^{T} A^{T} A x-2 b^{T} A x+b^{T} b \tag{4}
\end{equation*}
$$

Taking the derivative gives:

$$
\begin{equation*}
2 A^{T} A x-2 A^{T} b=0 \tag{5}
\end{equation*}
$$

which gives us the desired result $\square$

## Minimum norm

Suppose we have an underdetermined set of equations:

$$
\begin{equation*}
A x=b \tag{6}
\end{equation*}
$$

where $|b|<|x|$ (there are less points $b$ than parameters $x$ ). The idea is to find $\hat{x}$ that satisfies $A x=b$ and minimizes $\|x\|_{2}$. This is given by:

$$
\begin{equation*}
\hat{x}=A^{T}\left(A A^{T}\right)^{-1} b \tag{7}
\end{equation*}
$$

Proof is left as an exercise.

## Minimum Variance Estimates

Find the estimate that minimizes the variance of the error

## Example

Given two measurements, $m_{1}$ and $m_{2}$ of $m$, each with independent, zero mean Gaussian measurement errors, $\sigma_{1}$ and $\sigma_{2}$, find the minimum variance estimate $\hat{m}$ using the form:

$$
\begin{equation*}
\hat{m}=\alpha_{1} m_{1}+\alpha_{2} m_{2} \tag{8}
\end{equation*}
$$

## Example, contd

## Solution

(1) Because the solutions are unbiased, $\alpha_{1}+\alpha_{2}=1$ (otherwise there will be an error in the mean value).
(2) The variance of $\hat{m}$ is

$$
\begin{equation*}
\alpha_{1}^{2} \sigma_{1}^{2}+\alpha_{2}^{2} \sigma_{2}^{2}=\left(1-\alpha_{2}\right)^{2} \sigma_{1}^{2}+\alpha_{2}^{2} \sigma_{2}^{2} \tag{9}
\end{equation*}
$$

Minimizing this gives $-2\left(1-\alpha_{2}\right) \sigma_{1}^{2}+2 \alpha_{2} \sigma_{2}^{2}=0$ and

$$
\begin{equation*}
\alpha_{2}=\frac{\sigma_{1}^{2}}{\sigma_{1}^{2}+\sigma_{2}^{2}} \tag{10}
\end{equation*}
$$

## Gauss-Markov Estimate

In general, suppose that we have vectors $y, \beta$ and $\epsilon$, and a measurement matrix $W$ related by

$$
\begin{equation*}
y=W \beta+\epsilon \tag{11}
\end{equation*}
$$

$y$ is the measured quantity, $\beta$ are the underlying systen parameters, and $\epsilon$ is the measurement noise, with covariance $Q$.
The minimum variance unbiased estimate is

$$
\begin{equation*}
\hat{\beta}=\left(W^{T} Q^{-1} W\right)^{-1} W^{T} Q^{-1} y \tag{12}
\end{equation*}
$$

with covariance

$$
\begin{equation*}
\mathbf{E}\left[(\hat{\beta}-\beta)(\hat{\beta}-\beta)^{T}\right]=\left(W^{T} Q^{-1} W\right)^{-1} \tag{13}
\end{equation*}
$$

## General Minimum Variance Estimate

Suppose, as in the previous slide, that

$$
\begin{equation*}
y=W \beta+\epsilon \tag{14}
\end{equation*}
$$

$y$ is the measured quantity, $\beta$ are the underlying systm parameters, and

$$
\begin{align*}
\operatorname{Cov}\left[\epsilon \epsilon^{T}\right] & =Q  \tag{15}\\
\operatorname{Cov}\left[y y^{T}\right] & =P \tag{16}
\end{align*}
$$

e.g, there is errors in $y$. The minimum variance unbiased estimate is

$$
\begin{equation*}
\hat{\beta}=\left(P^{-1}+W^{\top} Q^{-1} W\right)^{-1} W^{\top} Q^{-1} y \tag{17}
\end{equation*}
$$

## Maximum likelihood estimates

Another approach to finding estimates - choose estimate $\hat{x}$ that is the most likely
Steps:
(1) 1. Write the probability distribution function for $x$.
(2) 2. Maximize the probability distribution function
(3) $\rightarrow$ the Maximizer is the ML estimate

## Example

Given two measurements, $m_{1}$ and $m_{2}$ of $m$, each with independent Gaussian measurement errors, $\sigma_{1}$ and $\sigma_{2}$, find the maximum likelihood estimate $\hat{m}$.

## Solution

The pdf of $m_{1}$ and $m_{2}$ is given by:

$$
\begin{equation*}
p(m)=\prod_{i} \frac{1}{\sigma_{i} \sqrt{2 \pi}} \exp \left(-\frac{1}{2 \sigma_{i}^{2}}\left(m_{i}-m\right)^{2}\right) \tag{18}
\end{equation*}
$$

Taking the log yields:

$$
\begin{equation*}
p(m)=-\sum_{i}\left(\log \left(\sigma_{i} \sqrt{2 \pi}\right)\right)+\sum_{i}\left(-\frac{1}{2 \sigma_{i}^{2}}\left(m_{i}-m\right)^{2}\right) \tag{20}
\end{equation*}
$$

## Example contd

The ML estimate is the value of $m$ that maximizes:

$$
\begin{equation*}
p(m)=-\sum_{i} \log \left(\sigma_{i} \sqrt{2 \pi}\right)+\sum_{i}\left(-\frac{1}{2 \sigma_{i}^{2}}\left(m_{i}-m\right)^{2}\right) \tag{22}
\end{equation*}
$$

Differentiating with respect to $m$ gives:

$$
\begin{equation*}
\frac{1}{\sigma_{1}^{2}}\left(m_{1}-m\right)+\frac{1}{\sigma_{2}^{2}}\left(m_{2}-m\right)=0 \tag{23}
\end{equation*}
$$

and that

$$
\begin{equation*}
\hat{m}=\frac{\sigma_{2}^{2}}{\sigma_{1}^{2}+\sigma_{2}^{2}} m_{1}+\frac{\sigma_{2}^{1}}{\sigma_{1}^{2}+\sigma_{2}^{2}} m_{2} \tag{24}
\end{equation*}
$$

This is equivalent to the minimum variance estimate.

